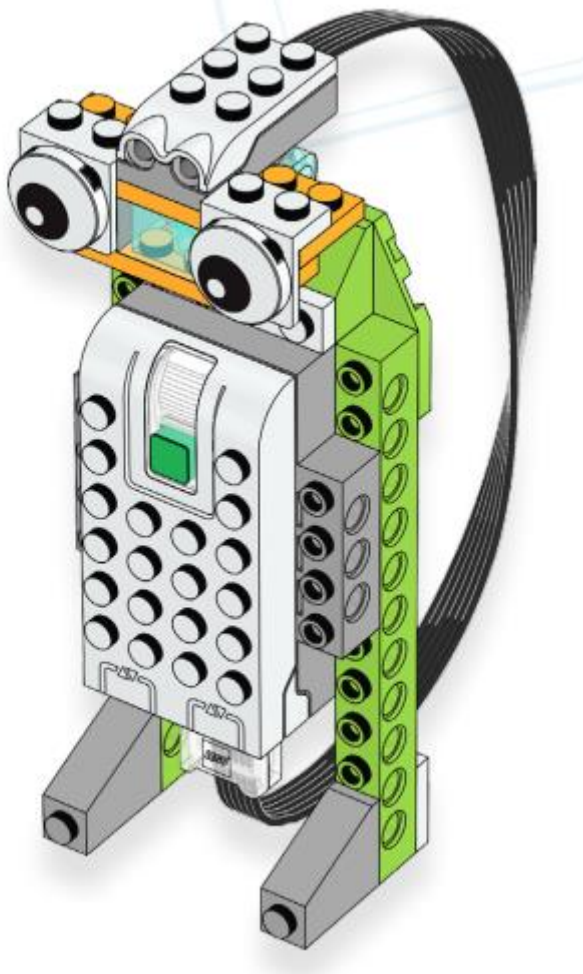
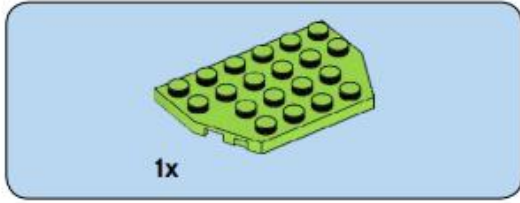


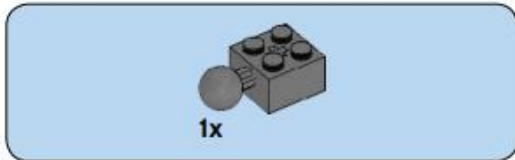
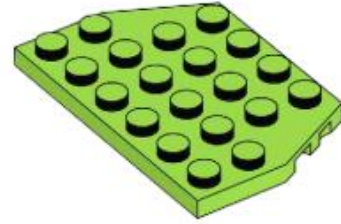
Capítulo 4 (Spy Robot) Robot espía



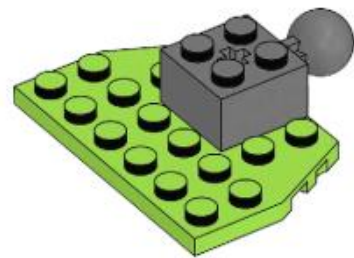
Este capítulo se puede realizar con un kit.

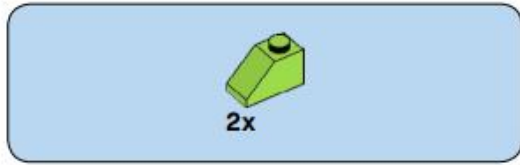


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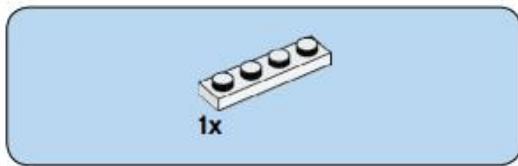
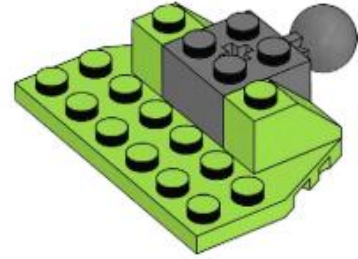


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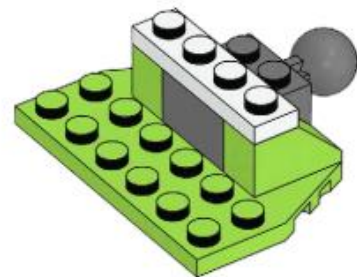


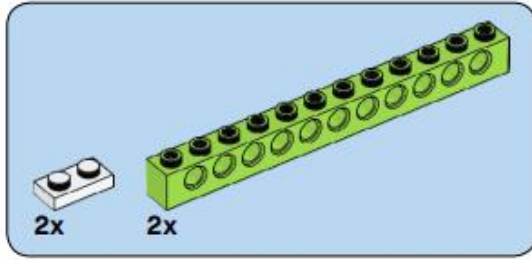


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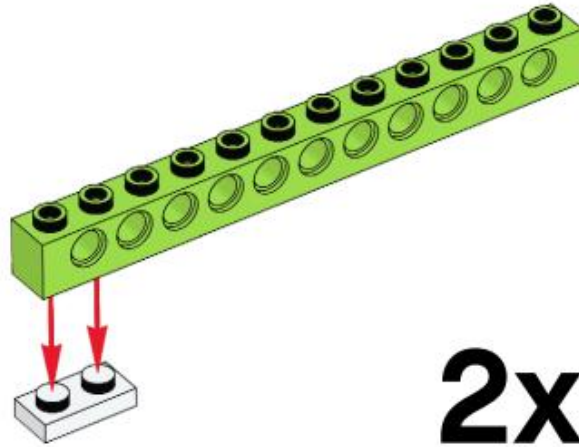


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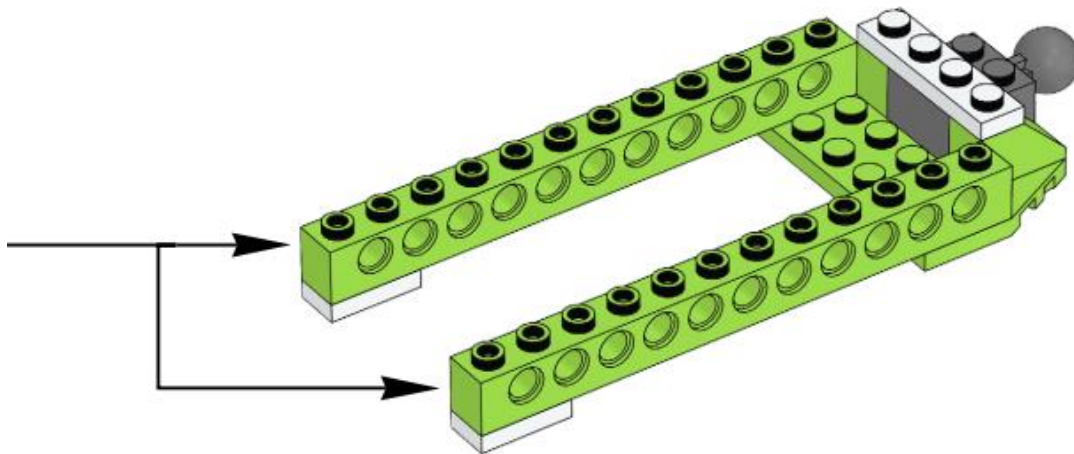


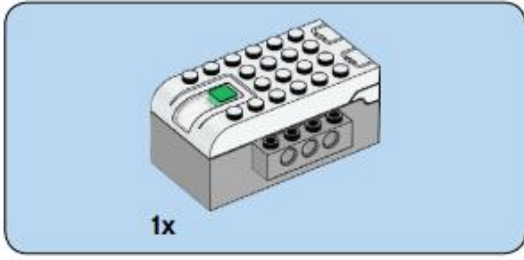


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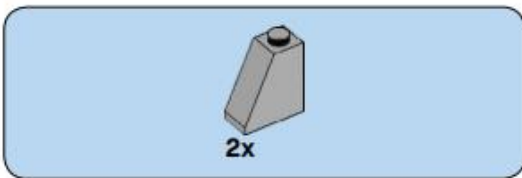
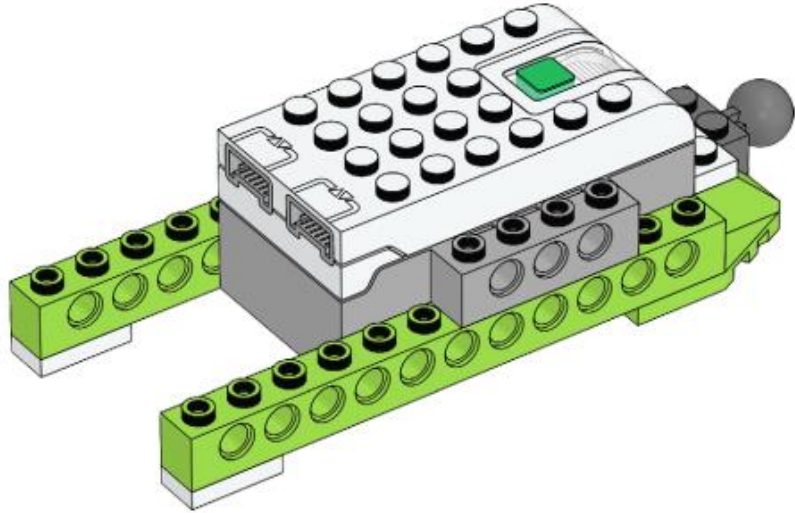


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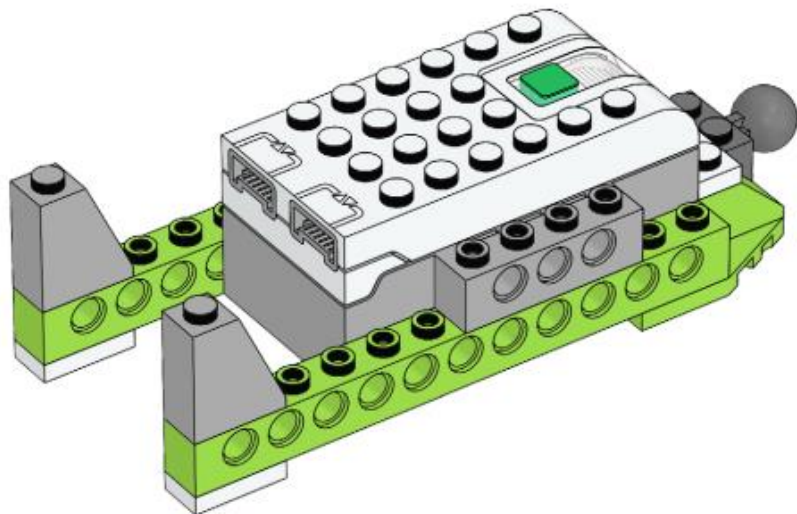


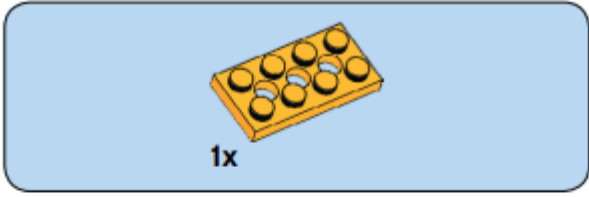


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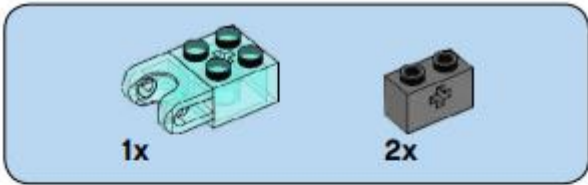
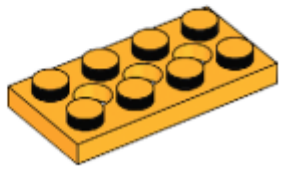


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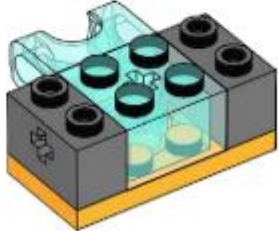


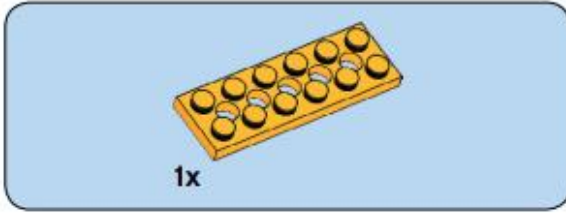


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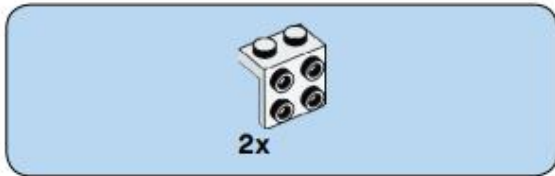
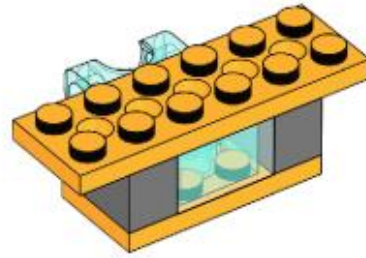


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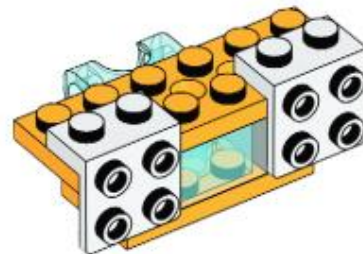


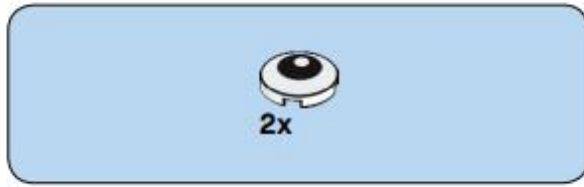


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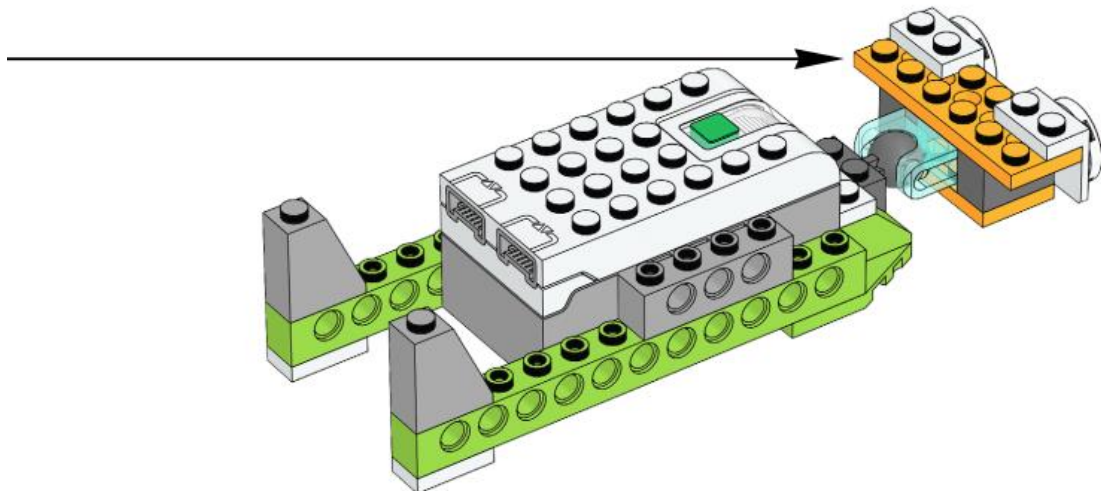


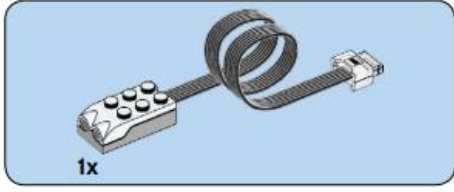


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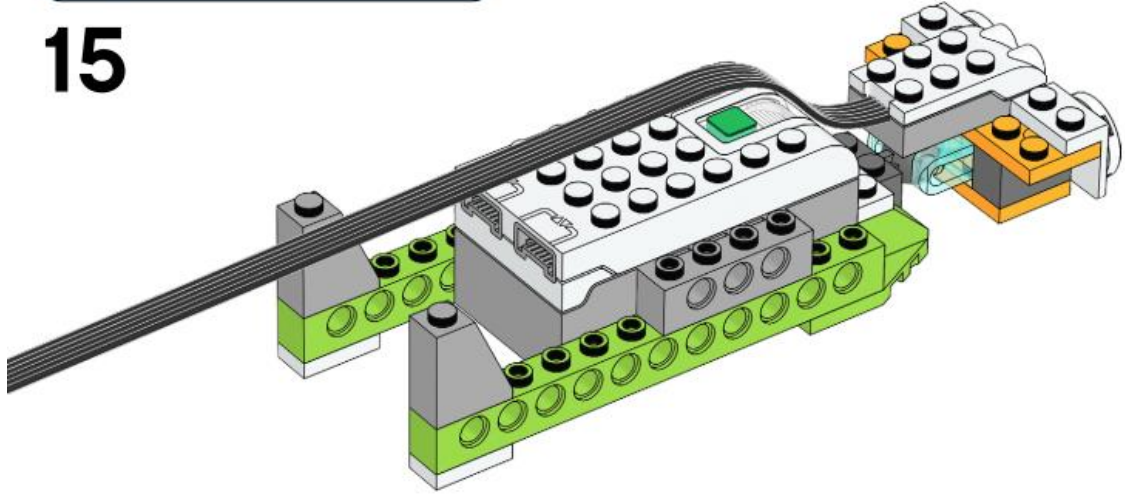


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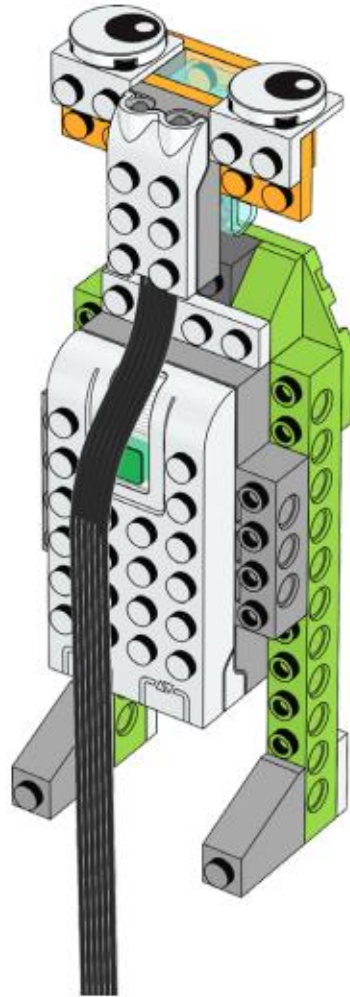




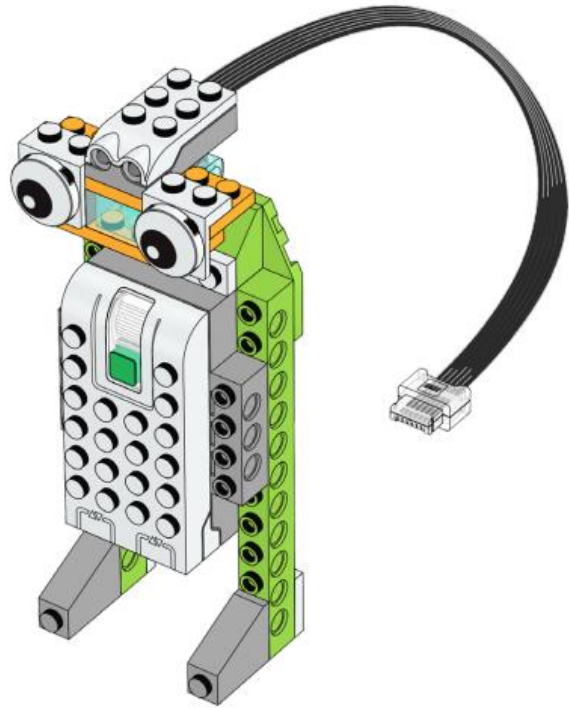
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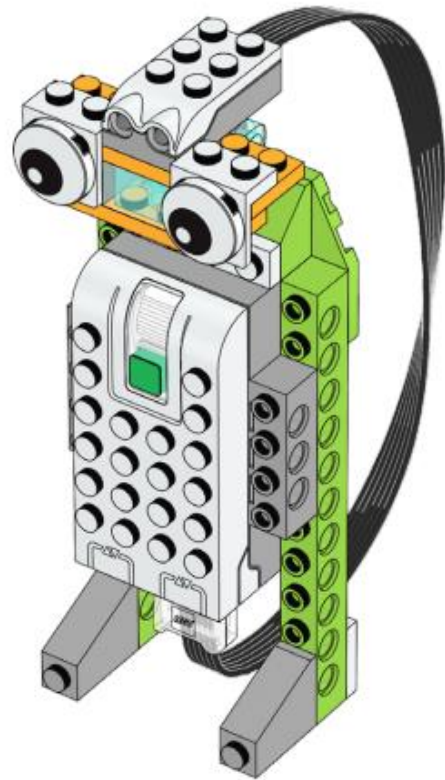
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17



18

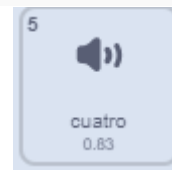
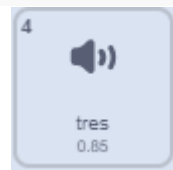
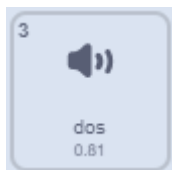
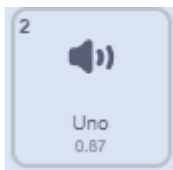
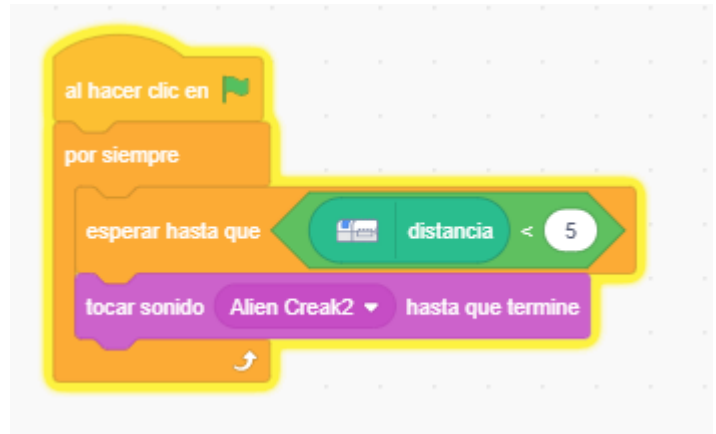


Codificación

En este capítulo le hemos insertado el detector de objetos, queremos que cuando le aproximemos la mano, nuestro robot realice un sonido. →

Para los más avanzados vamos a realizar el correspondiente programa.

Tenemos que grabar 4 mensajes 1, 2, 3 y 4. →



Ahora según tengamos la distancia nos diga el correspondiente mensaje.



